## **ELEVATOR MOTORS CORPORATION**

### PROGRAMMING INSTRUCTIONS

# LOAD WEIGHING CONTROLS MODEL VK- 3I or VK- 3V

## 1. Description of Operation

The purpose of EMCO Load System is to measure, monitor and provide usable information about the load in an elevator cab. This information can be used to protect the passengers from overload conditions and increase the efficiency of the elevator. The system usually consists of a sensor or group of sensors to be mounted on the elevator and a controller. The sensor(s) are used to provide a signal to the controller directly related to the amount of load in the cab. The controller is used to accept this signal and provide usable data to the elevator controller in the form of relays, analog signals or other methods of communication.

## 2. Electrical Characteristics

<u>Model</u>	Power Supply	Current	<u>Fuse</u>
VK-3I, 3V	220VAC	60mA	100mA
	115 VAC	120mA	200mA
	24VDC	300mA	800mA

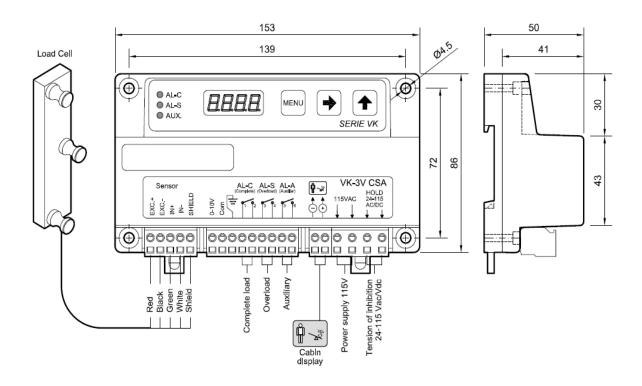
### 3. Contents

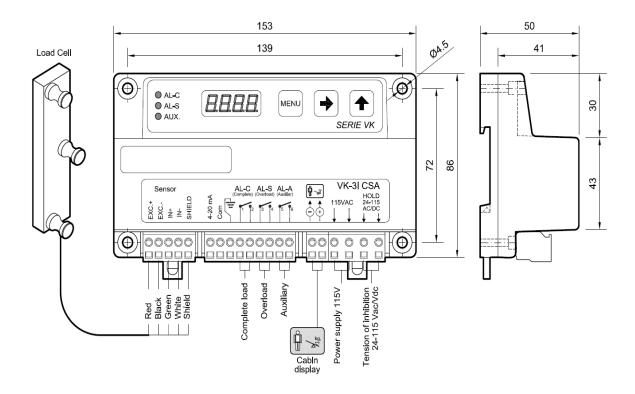
1 pc- VK Controller, 1 pc- DIN Rail Mount, 2 pc- Rail Mounting Screws,

1 pc- Terminal Tool/Key, 1 pc- Terminal Cover

## 4. Installation

Wiring diagrams and dimensions





# 5. Description of Connections

**AL-C**, **AL-S** and **AL-A** (if provided) are the relays that change state when the programmed weight values are exceeded.

- RL [] is usually programmed for the capacity of the cab. When the load in the cab exceeds this value the relay changes state and if using our MB-D display the figure will illuminate as the load increases. Analog output of this setting is 20Ma or 10Vdc.
- RL 5 is usually programmed for overload. When the load in the cab exceeds this value the relay changes state and if using our MB-D display it will activate a buzzer and the KG marking of the display will illuminate.
- $\boxed{\text{RL}}$   $\boxed{\text{R}}$  is an extra relay to be programmed as needed. When the load in the cab exceeds this value the relay changes state.

**Hold** is a circuit that requires 24-110VAC or VDC power. The power is to be applied when the doors close and the power is to be removed when the doors open. When power is applied the control stops weighing and the weight value will blink on the display. This insures that movement of the cab will not affect the weighing process. Also, when the doors are closed since no more people will be entering the cab there is no reason to continue the weighing process. When the doors open, power is to be removed from the hold circuit so that the control can begin measuring the load in the cab.

**Power Supply** required to operate the controller is shown above the terminals. Standard voltages are 24VDC, 110VAC and 220VAC depending on the control ordered.

**Sensor** connections are shown above the terminals on the controller corresponding to the load sensor/cell used.

**Cabin Display-** Our MB Display is the factory supplied display that can be used with the VK Series of controllers. Based upon the setting of AL-C relay the figure will progressively illuminate starting at the feet and travel up the body of the figure. Upon reaching the setting of AL-C the complete figure will be illuminated. The KG marking will illuminate and a buzzer will sound upon reaching the AL-S relay setting of the control. If you want to use your own buzzer or LED display connect to these terminals. These terminals provide 0-7.5 VDC at 75mA maximum based upon the settings of the **AL-C** and **AL-S** settings. When connecting your own buzzer of LED display follow polarity as shown on terminals.

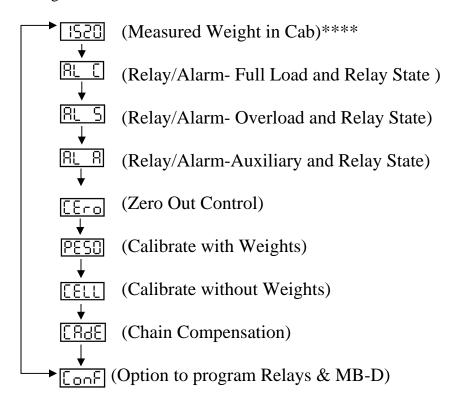
## 6. Programming Keys

- Pressing the menu key scrolls through the various programmable parameters of the control.
- Pressing this key enters the specific parameter you are going to program. Once the specific parameter is displayed, pressing this key highlights the digit to be modified.
- Pressing this key will modify the specific digit.

## 7. Menu/Programming Order

## **Installation Menu**

Pressing the **Key** will scroll through the Installation Menu program in the following order:



\*\*\*\*\*Note: Actual value displayed varies with load in cab

## 8. How to Program

Button/Key Operation

- Press the changed. **Key** until the display shows the desired parameter to be
- Press the **E Key** to highlight the specific digit to be modified. The digit to be modified will blink.
- Press the **Key** to change the specific digit.
- Press the **Key** twice to save the new value. Once a value is saved the control will display the next parameter.
- If you do not press the **Key** twice the changes will not be stored and the controller display will remain at the parameter you were modifying.

### 9. Calibration

## **Manual Calibration with Weights**

- 1. Before programming or calibrating sensors and control:
  - Bring cab to middle floor of its total travel. For instance, if travel is 6 stops or floors place cab on the 3<sup>rd</sup> or 4<sup>th</sup> floors.
  - Bounce in cab to insure cab is free on guide rails.
- 2. Properly connect the sensors to control.
- 3. Power up control and check power supply to control and insure within voltage range of the control supplied.
- 4. Install sensors to cable per instructions supplied with sensors.
- 5. **Zero out the controller**:
  - Press **Key** till **Effo** is displayed.
  - Press **E Key** once.
  - Press MENU Key once.
  - Controller display will begin to count down. Exit top of cab till unit finishes counting down.
  - PESO should be shown on the display. If PESO is not shown the value has not been saved in the controller and this step must be done again.

#### 6. Adjust for weights:

- Press **Key** till **PESO** is displayed if it is not shown.
- Add a known weight to the car. Preferably a minimum of **50%** of the car capacity.
- Press and Keys to manually enter the value in kilograms of the weight in the cab.
- Press MENU Key twice.
- As controller display begins to count down, exit top of cab till unit finishes counting down.
- Press the key until the weight is shown on control display. It should be the value of the weights in the cab in kilograms.

- 7. **Set AL-C** Contact trip level:
  - Press **Key** till **AL** [ is displayed.
  - Press and **Keys** to set contact trip point values. Put the value in kilograms of the weight that will activate the relay. Usually for the **AL-C** contact the capacity of the cab is used.
  - Press Key and Key to set the contact as normally open or normally closed. The display shows Off or On. Off is a normally open contact and On is a normally closed contact.
  - Press Key twice to save these settings.
- 8. Repeat **Step 7** for the other contacts to be used. AL S is normally the overload setting and AL A is an auxiliary contact to be set as needed by customer.
- 9. Complete any other wiring including hold circuit and any other auxiliary programming.

# **Auto Calibration without Weights (CH or CHD Hydraulic Sensors Must Use Manual Calibration)**

- 1. Before programming or calibrating sensors and control:
  - Bring cab to middle floor of its total travel. For instance, if travel is 6 stops or floors place cab on the 3<sup>rd</sup> or 4<sup>th</sup> floors.
  - Bounce in cab to insure cab is free on guide rails.
- 2. Connect sensors to control. Power up control and check power supply to control and insure within voltage range of the control supplied.
- 3. Install sensors to cable per instructions supplied with sensors.
- 4. **Zero out** the controller:
  - Press Key till Ero is displayed.
  - Press **E Key** once.
  - Press Key once.
  - Controller display will begin to count down. Exit top of cab till unit finishes counting down.
  - PESO should be shown on the display. If PESO is not shown the value has not been saved in the controller and this step must be done again.
- 5. Enter **CELL Value** by:
  - Press **Key** till **ELL** is displayed.
  - Locate the **CELL** value shown on the connection box of the sensors.
  - Press the **Key** once.
  - Press the and Keys to enter the CELL value shown on the connection box of the sensors into the controller. If 2:1 roped application double the value of the cell shown on the connection box of the sensors.
  - Press the Key twice to save the CELL value in the controller.
  - LAGE should be shown on the display. If LAGE is not displayed the value of the LELL has not been saved and this step must be done again.
- 6. Set **AL-C** Contact trip level:
  - Press MENU Key till AL [] is displayed.

- Press and keys to set contact trip point values. Put the value in kilograms of the weight that will activate the relay. Usually for the AL-C contact the capacity of the cab is used.
- Press key and Key to set the contact as normally open or normally closed. The display shows Off or On. Off is a normally open contact and On is a normally closed contact.
- Press Key twice to save these settings.
- 7. Repeat Step 7 for the other contacts to be used. AL S is normally the overload setting and AL A is an auxiliary contact to be set as needed by customer.
- 8. Complete any other wiring including **hold** circuit and any other auxiliary programming.

# 10. Auxiliary Options:

- [RB] This allows you to enter a value if there is compensation chain on the elevator. The maximum value that can be entered for compensation chain is 50kg. To enter a value for compensation chain into the control:
  - o Press the **Key** till **[838]** is displayed.
  - o Press the and Keys to enter the compensation chain value you desire.
  - o Press the Key twice to save the value in the controller.
  - o Fight should be shown on the display. If **ConF** is not displayed the value for the compensation chain is not saved and this step must be done again.
- This option allows you to program the **MB-D** Display different than supplied by the factory. See factory for details

# 11. Troubleshooting and Errors

- Elevator will not run- Check for any **Err codes** on the display. If there are any Err codes read this section further. If no Err codes, check all controller connections and make sure the proper voltage is provided to power connections. Then check the proper voltage is supplied to the hold circuit and insure the proper sequence of power applied to the hold circuit. Then check fuse. To check fuse, disconnect power to the controller, open the controller by removing the five (5) screws that hold the cover, remove fuse from vertical free mounting (black) fuse holder next to controller transformer and replace with new fuse.
- Erri = Bad load cell connection or damaged load cell- Correct error condition by checking all load cell connections to the controller are per wiring diagram along with inspecting cables for any cuts or broken wires.

- Err2 = Negative load cell flow- Correct error condition by checking load cell connections to the controller and insure they are per wiring diagram.
- [Err] = Positive load cell flow- Load cells are to small for application and must be replaced with proper units.
- Erry = Polarity error- Correct error condition by checking all load cell connections to the controller are per wiring diagram and reprogram control.
- Err5 = MB-D display short- Correct condition by locating short. Disconnect MB-D display, turn off the controller and reconnect the MB-D display.
- Errs = Loss of data in memory- Correct condition by programming controller again.
- Erra = Sensitivity of load cell is small. Recalibrate and reprogram operation, add known weight into car and reprogram PESO operation per Paragraph 9.

#### FOR ANY FURTHER ASSISTANCE OR IF ANY QUESTIONS CONTACT:

ELEVATOR MOTORS CORPORATION 80 CAROLYN BOULEVARD FARMINGDALE, NY 11735-1525 PH (631) 293-4220, FAX (631) 293-2714 E- Mail info@elevatormotors.com

